

i/o description

UNIVAC
MILITARY COMPUTERS

MILITARY COMPUTERS i/o description

CONTENTS

	Page
INTRODUCTION	1
FUNCTIONAL INTERFACE	1
General Information	1
Control Communication	2
Definition of Control Signals	3
Sequence of Input/Output Events	3
Data Output	3
Function Output	4
Data Input	4
Interrupt Input	5
COMPUTER-TO-COMPUTER INTERFACE	6
Data and Control Signals	6
Definition of Control Signals	6
Sequence of Events – Information Transfers	6
Function Word Transfers (Commands)	6
Data Transfers	7
ELECTRICAL INTERFACE	8
Input and Output Functional Specifications	8
Minus 15 Volt Interface – Input and	
Output Circuit Specifications	9
General System Considerations	10
Minus 3 Volt Interface – Input and	
Output Circuit Specifications	10
Plus 3.5 Volt Interface – Input and	
Output Circuit Specifications	11
Timing of Input and Output Data and Control Lines ...	13
Output of Data and External Equipment Commands	13
Input of Data and Interrupt Status Codes	
to Computer	14
PHYSICAL INTERFACE	17
Interconnecting Cables	21
Cable Connectors	21

ILLUSTRATIONS

Figure		Page
1	Computer-To-Peripheral Equipment Interface	3
2	Computer-To-Computer Interface	6
3	-15 Volt Interface Timing	12
4	Output Data and External Function Timing (-3.0 Volt Interface) (+3.5 Volt Interface)	15
5	Input Data and External Interrupt Timing (-3.0 Volt Interface) (+3.5 Volt Interface)	16

TABLES

Table		Page
1	Control Signals Used in Input/Output	2
2	Control Signals Used in Intercomputer Communication	7
3	I/O Control and Data Line Timing	18
4	Interface Circuits and Cable Lengths	19
5	Connector Pin Assignments	20
6	Cable and Cabinet Connectors	21

INTRODUCTION

This document is a guide for the design of the electrical interface in a peripheral device that will communicate with UNIVAC[®] Military Computers. Any unit of peripheral equipment (or another computer) that is to communicate with these computers on an input or output channel must comply with the applicable requirements. Since this document includes data on a number of computers, certain individual requirements apply for the capability discussed. It is limited to interface characteristics; i.e., physical, functional, and electrical; it does not describe the input/output section of any equipment.

The Functional Interface subsection explains the philosophy of equipment input and output procedures. Following this the Electrical Interface discussion establishes the functional and timing specifications applicable thereto.

The timing data specified herein should not be considered typical or actual. Values denoting minimum time should be interpreted as such. The response of certain computers and other devices used as peripherals may be significantly slower but may not be faster if positive response is expected.

FUNCTIONAL INTERFACE

GENERAL INFORMATION

All references to input or output in this discussion of Functional Interface are made from the standpoint of the computer; that is, input is always input to the computer and output is always output from the computer.

Communication with the computer is carried on in a parallel mode over the input/output channels. These channels are assembled in groups, each of which contains four identical input/output channels. Two different types of operation can be used with the computers: one communicates with the peripheral equipment only, and the other communicates either with peripheral equipment or with another computer. The conversion from a standard peripheral equipment channel to inter-computer communication, externally specified index or externally specified address mode of operation requires input/output circuit changes of varying complexities in the different computers (viz., switch change, P.C. card or chassis change, etc.).

The output registers (one for each group) hold information for peripheral equipment during out-

put or external function transfers. Each acts as a buffer register for four output channels. Peripheral devices similarly must provide a buffer register to hold information on the input lines of the computer until it can gate that information into memory.

Any one of the operating groups can be provided with a -3 volt, or -15 volt interface and some have an additional +3.5 volt option. Computers with dual channel operation capability must have the same interface on both affected groups if dual channel operation is used.

The -15 volt interface provides communications transfer rates of up to a maximum of 41,667 words per channel. The -3 volt and +3.5 volt provide transfer rates of up to the maximum capability of the computer. Individual equipment specifications list the applicable transfer rates.

The transfer of input and output data words is asynchronous or in parallel with the computer program. In some computers, transmission of External Functions may be handled the same as data transmission. To utilize this method, the peripheral

equipment must set a line indicating it is capable of accepting a command word from a buffer; therefore, the transmission of the word need not be synchronized with the computer program. Transmission of External Functions to equipment not containing logic for requesting functions (commands) is provided by the Force External Function instruction in the computer repertoire.

CONTROL COMMUNICATION

Each of the input channels and output channels communicates over an associated cable containing information lines plus control lines. The computer is designed to use a d-c level input/output system. Signals are d-c levels which may be changed upon interchange of control or data information.

TABLE 1. CONTROL SIGNALS USED IN INPUT/OUTPUT

	SIGNAL NAME	ORIGIN	MEANING
Input Channel	External Interrupt Enable (EIE)*	Computer	"I have enabled my input section to honor an Interrupt from you"
	Input Data Request (IDR)	Peripheral Equipment	"I have a data word on your input lines ready for you to accept."
	Input Acknowledge (IA)	Computer	"I have sampled the word from you."
	External Interrupt Request (EIR)	Peripheral Equipment	"I have an Interrupt code word on your input lines ready for you to accept."
Output Channel	Output Data Request (ODR)	Peripheral Equipment	"I am in a condition to accept a word of data from you."
	Output Acknowledge (OA)	Computer	"I have put a data word for you on my output lines; sample them now."
	External Function Request (EFR)*	Peripheral Equipment	"I am in a condition to accept an External Function message from you."
	External Function Acknowledge (EFA)	Computer	"I have put an External Function message for you on my output lines; sample them now."

*See applicable equipment specifications.

DEFINITION OF CONTROL SIGNALS

The control signals used for input and output operation are defined in Table 1, and the lines which carry them are similarly identified. These control lines are called in the same way as the data lines and have the same voltage levels. Equipment recognizes each "1" received on any control line (except the Interrupt Enable line) by detecting the change in voltage level of the signal. It does not recognize another "1" on that control line until its circuitry has been reset by a change in the voltage level of the signal in the opposite direction (a "0"). All control signals are detected by the input amplifier circuit as a transition except that for the External Interrupt Enable line, the input logic of peripheral equipment need not detect the transition but rather the actual state of the signal on the line. Some computers are equipped with External Interrupt Enable logic and some peripheral devices are designed with External Function Request logic for those respective interface lines. (See applicable equipment specifications.)

SEQUENCE OF INPUT/OUTPUT EVENTS

An input/output channel will transfer control and data words by means of the reciprocal interaction specified herein for each form of communication. Examples will clarify the use of the control lines.

Figure 1 shows the computer communicating with peripheral equipment over both input and output cables. "Request" signals always originate at the peripheral equipment. "Acknowledge" and "Enable" signals always originate at the computer.

The sequence of events for each of the four cases of communication between the computer and peripheral equipment is given below. The order of steps a) and b) may be interchanged when an input/output or function buffer sequence is initiated.

Data Output

A normal output sequence for data transfer from computer-to-peripheral equipment (buffer mode) is as follows:

- a) Computer initiates output data buffer for given channel;
- b) Peripheral equipment sets the Output Data Request line when it is in a condition to accept data;
- c) Computer detects the setting of the Output Data Request line;
- d) In accordance with internal priorities, the computer places a word of data on the Output Data lines;

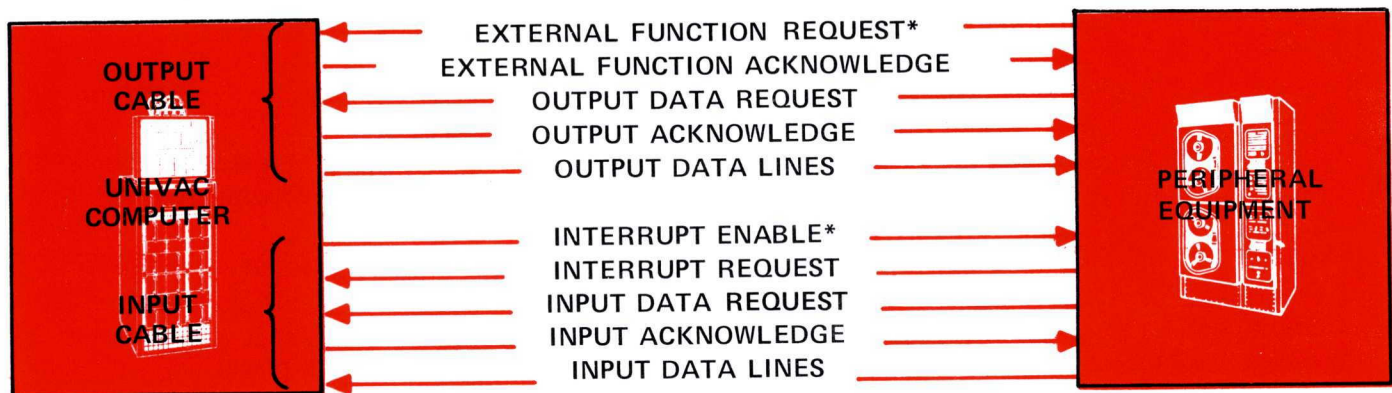


FIGURE 1. COMPUTER-TO-PERIPHERAL EQUIPMENT INTERFACE

*See applicable equipment specification.

- e) Computer sets the Output Acknowledge line to indicate that a word of data is on the Output Data lines;
- f) Peripheral equipment detects the setting of the Output Acknowledge line;
- g) Peripheral equipment may clear the Output Data Request line any time after detecting the setting of the Output Acknowledge line but it must clear the Output Data Request line before the computer will recognize the next Output Data Request;
- h) Peripheral equipment reads the data word which is on the Output Data lines;
- i) Computer clears the Output Acknowledge line before it places the next word on the Output Data lines.

Steps b) through i) of this sequence are repeated for every data word until the number of words specified in the output buffer have been transferred.

Function Output

The following sequence of events occurs when the computer is transmitting External Function messages to external equipment (buffer mode):

- a) Computer initiates External Function buffer for given channel;
- b) Peripheral equipment sets the External Function Request line indicating that it is in a condition to accept External Function messages;*
- c) Computer detects External Function Request;
- d) Computer places an External Function message on the output information lines according to internal priority;

*Peripheral equipment not equipped with External Function Request logic should have the ability to accept Forced External Functions when in the Idle or Ready state by responding to sequence steps d), e), f), and h).

- e) Computer sets the External Function Acknowledge line indicating that an External Function message is ready for sampling;
- f) Peripheral equipment detects the External Function line change to the "1" state;
- g) Peripheral equipment may clear the External Function Request any time after detecting the External Function;
- h) Peripheral equipment samples the External Function message on the information lines;
- i) Computer clears the External Function Acknowledge line before it places another word on the output lines.

Steps b) through i) of this sequence are repeated for every External Function message until the number of words specified in the External Function buffer have been transferred.

Whenever the current instruction of the computer program is a "Force External Function" or a "Force Output" instruction, the computer will transfer to the peripheral device on the specified channel that function or data word specified by the Buffer Control Word whether or not the respective request line is set (if such line exists on that channel). The peripheral device must respond to the events of steps d), e), f), h), and i) of the applicable output sequence.

Data Input

Normal input sequence for data transfer to the computer with peripheral equipment is as follows:

- a) Computer initiates input data buffer for given channel;
- b) Peripheral equipment places a word of data on the Input Data lines;

- c) Peripheral equipment sets the Input Data Request line to indicate that a word of data is on the Input Data lines;
- d) Computer detects the setting of the Input Data Request line;
- e) In accordance with internal priorities, the computer reads the data word which is on the Input Data lines;
- f) Computer sets the Input Acknowledge line indicating that it has read the data word on the Input Data lines;
- g) Peripheral equipment detects the setting of the Input Acknowledge line;
- h) The peripheral equipment may clear the Input Data Request line any time after detecting the setting of the Input Acknowledge line, but it must clear the Input Data Request before the computer will recognize the next Input Data Request;
- i) Computer clears the Input Acknowledge line before it reads the next word on the Input Data lines.

Steps b) through i) of this sequence are repeated for every data word until the number of words specified in the input buffer have been transferred.

Interrupt Input

Sequence for transmitting an Interrupt from peripheral equipment to the computer is as follows:

- a) Computer sets the External Interrupt Enable line when it is ready to accept an External Interrupt;
- b) Peripheral equipment detects the state of the External Interrupt Enable line;

- c) If peripheral equipment status requires computer to be interrupted, it places an External Interrupt Code word on the Input Data lines;
- d) Peripheral equipment sets the External Interrupt Request line to indicate that the External Interrupt Code word is on the Input Data lines;
- e) Computer detects the setting of the External Interrupt Request line;
- f) In accordance with internal priorities, the computer reads the External Interrupt Code word which is on the Input Data lines;
- g) Computer clears the External Interrupt Enable line;
- h) Computer sets the Input Acknowledge line;
- i) Peripheral equipment detects the setting of the Input Acknowledge line;
- j) The peripheral equipment may clear the External Interrupt Request line any time after detecting the setting of the Input Acknowledge line, but it must clear the External Interrupt Request line before the computer will recognize the next External Interrupt Request;
- k) Computer clears the Input Acknowledge line before it reads the next word on the Input Data lines.

The Input Acknowledge of an Interrupt will be initiated at approximately the same time that the External Interrupt Enable is cleared. The synchronized occurrence of these conditions should be used by peripheral equipment to differentiate between the "Acknowledge" of an Interrupt Request and the "Acknowledge" of a data Input Request. Peripheral devices not equipped with Interrupt Enable logic may interrupt the program by using sequence steps c), d), e), f), h), i), j), and k). Computers not equipped with the External Interrupt Enable line will respond in like manner.

COMPUTER-TO-COMPUTER INTERFACE

DATA AND CONTROL SIGNALS

Since many input/output channels of the computer can be intercomputer channels, it is possible for a computer to communicate with a number of other computers. The control signals and lines governing intercomputer communication are shown in Figure 2 to illustrate the interface between two computers. Computer A is transmitting to Computer B. The selection of a given channel as an intercomputer channel affects only the logic concerned with the output and external function buffers. A channel, which is sending data or external function messages to a given peripheral equipment, holds the data in the output registers for a fixed minimum time period after which another Output or External Function Request on a channel can cause the data to be changed. However, an intercomputer channel sending data or External Function messages to another computer must hold the information in the output register until the receiving computer acknowledges receipt of those data or until an Intercomputer Time Out Interrupt in the transmitting computer permits a resolution. The acknowledge signal is received on what is known as the Output Request line when not in intercomputer mode. This line, in the intercomputer mode, is known as the Resume line.

DEFINITION OF CONTROL SIGNALS

The control signals in the input cable are the same for intercomputer communication as for communication with peripheral equipment. In the output cable, Ready and Resume signals are used to control intercomputer transfer of data. The control signals used for intercomputer communication are defined in Table 2. Computer A is assuming the output channel.

SEQUENCE OF EVENTS—INFORMATION TRANSFERS

The sequence of events for each of the two cases of intercomputer communication appears below.

Function Word Transfers (Commands)

Intercomputer command word transfer from Computer A to Computer B follows the sequence:

- Computer A initiates an External Function Buffer on the Intercomputer channel;
- Computer B sets its External Interrupt Enable when it is ready to accept a command word from Computer A;

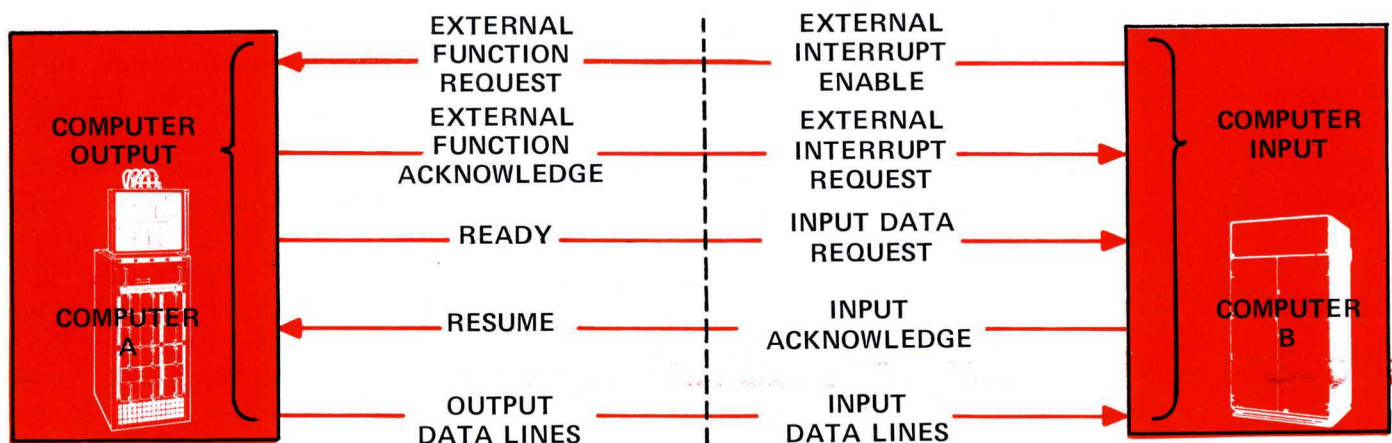


FIGURE 2. COMPUTER-TO-COMPUTER INTERFACE

TABLE 2. CONTROL SIGNALS USED IN INTERCOMPUTER COMMUNICATION

	SIGNAL NAME	ORIGIN	MEANING
Inter-computer Channel	External Interrupt Enable (EIE)	Computer B	"I have enabled my input section to honor a <u>com-mand</u> word from you."
	Ready	Computer A	"I have a data word on your input lines ready for you to accept."
	Resume	Computer B	"I have sampled my input lines."
	External Interrupt Request (EIR)	Computer A	"I have a <u>command</u> code word on your input lines ready for you to accept."

(All other lines are the same as for peripheral equipment communication)

- c) Computer A recognizes the Interrupt Enable as an External Function Request in accordance with internal priorities;
- d) Computer A places an External Command word on the Output Data lines;
- e) Computer A sets the External Function Acknowledge line to indicate that the External Command word is on the Data lines;
- f) Computer B detects the setting of the External Function Acknowledge line and interprets it as an External Interrupt Request;
- g) In accordance with its internal priorities, Computer B reads its Input Data lines;
- h) Computer B sets its Input Acknowledge line to indicate that it has sampled the Data Lines;
- i) Computer B clears its Interrupt Enable line (synchronized with h);
- j) Computer A recognizes the Input Acknowledge as a Resume and clears its External Function Acknowledge line before it places another word on the Output Data lines;

- k) Computer B clears its Input Acknowledge line before it reads the next word on its Input Data lines.

Not all computers have the External Interrupt Enable line (refer to appropriate computer technical description). In the event that Computer A sets the External Function line while the Interrupt Enable line is cleared, or does not exist (this is possible when a "Force External Function" instruction is used), all communications on the associated group of output channels in A will be suspended until Computer B acknowledges receipt of the External Interrupt or until an Inter-computer Time-out Interrupt in A permits A to resolve the problem. Computers not connected with External Interrupt Enable logic transmit functions by using steps d), e), f), g), h), j), and k) of the above sequence.

Data Transfers

Intercomputer data transfer from Computer A to Computer B follows the sequence:

- a) Computer B initiates an input buffer and Computer A initiates an output buffer for

the required channel. The output buffer of Computer A must be less than or equal to the input buffer of Computer B;

- b) Computer A places a data word on its Output Data lines;
- c) Computer A sets the Ready line to indicate that the data are on the lines;
- d) Computer B recognizes the Ready signal as an Input Data Request signal and according to its internal priorities, accepts the data word;

- e) Computer B sets the Input Acknowledge;
- f) Computer A recognizes the Input Acknowledge as a Resume signal and clears the Ready line before it places the next word on the lines;
- g) Computer B clears its Input Acknowledge line before it reads the next word transferred by Computer A.

Steps b) through g) of this sequence are repeated for every data word until the number of words specified in the output buffer have been transferred.

ELECTRICAL INTERFACE

INPUT AND OUTPUT FUNCTIONAL SPECIFICATIONS

The following basic rules apply to the timing and electrical interface characteristics of control signals and data lines between the computer and peripheral equipment.

- a) Data lines must be stable at the time they are gated into storage elements. They need not be cleared to the "zero" state between successive words as in the case with control lines. For output, the computer must provide a suitable delay between gating information to the output lines and raising the Output or External Function Acknowledge signals to ensure that data lines are stable for sampling any time the Output or External Function Acknowledge signals are set. For input, the computer may sample the data lines immediately.
- b) A Request signal, once set, must remain set until acknowledge in order to maintain synchronism in the transfer of data or interrupt codes between the units. If, however, loss of data is of secondary importance an
- c) All control lines must be resynchronized. That is, the control lines must return to the logical "zero" state between successive recognition of control signals. Resynchronization will be accomplished by sensing the control signal's transition from the "zero" to the "one" state and gating the generated signal with a steady "one" state of the control signal.
- d) An output circuit will be any circuit in the computer or in the peripheral equipment that applies data or control information to an intercommunication cable.
- e) An input circuit will be any circuit in the computer or in the peripheral equipment

Input Data Request may be dropped in favor of an External Interrupt Request when an urgent interrupt code is to be sent to the computer. The converse is also permitted. (Refer to page 17 for timing restrictions.) This case is philosophically similar to the computer sending a Forced External Function or Forced Output in that the computer risks destroying data or an unexecuted command.

that receives data or control information from an intercommunication cable.

- f) The input circuit will be such that if the input wire is disconnected, the effect will be as though a "zero" were present at the input.
- g) The binary "zero" and "one" voltage levels will be measured at the driving end terminals of an output circuit.

MINUS 15 VOLT INTERFACE – INPUT AND OUTPUT CIRCUIT SPECIFICATIONS

The -15 volt interface is characterized by nominal values of 0 volt and -15 volts to represent "1" and "0" respectively, and by a switching threshold of 6.0 ± 1.5 volts.

Each interface input amplifier circuit that takes its input from an interconnecting input cable must have the following characteristics:

- a) The output of the circuit will switch from "0" to "1" whenever the input signal changes in the positive direction through the range of -7.5 volts to -4.5 volts.
- b) The output of the circuit will switch from "1" to "0" whenever the input signal changes in the negative direction through the range of -4.5 volts to -7.5 volts.
- c) The output of the circuit will not switch as a result of any input transient pulse signal that has an integrated amplitude-duration of less than 15 volt-microseconds (delay of 1.5 ± 0.5 microseconds with a 15-volt step input).
- d) The output of the circuit will be "0" whenever its input is an open circuit.
- e) The circuit will not draw more than 4.0 milliamperes for a steady state "1" nor more than 1.0 milliamperes for a steady state "0".

- f) The output of the circuit will be "0" whenever the steady state input signal is more negative than -7.5 volts.
- g) The output of the circuit will be "1" whenever the steady state input signal is more positive than -4.5 volts.

Each interface output line driver circuit must have the following characteristics when driving a line with any capacitance of up to 6000* picofarads.

- a) The steady state output voltage representing "1" will be between -1.5 volts and +1.5 volts.
- b) The steady state output voltage representing "0" will be between -10.0 volts and -17.5 volts.
- c) The voltage variation among all "0" output signals or all "1" output signals on one channel will not exceed 1.0 volt.
- d)* The circuit will be capable of supplying 4.0 milliamperes for a steady state "1" output.
- e) The circuit will be capable of sinking 1.0 milliamperes for a steady state "0" output.
- f) The output of the circuit will switch in not more than 6.0 microseconds (measured between the 10 and 90 percent amplitude points).
- g) The output of the circuit will switch at a rate of not more than 5.0 volts per microsecond.
- h)* The circuit will be capable of driving the line and its termination (input amplifier) while switching as well as in the steady state condition.
- i) The control line driver circuit will present not less than 100,000 ohms impedance to the cable line whenever power is removed

*Each data line driver circuit that drives more than one line (e.g., four data lines per circuit in computers) must have proportionally more capability than specified here.

and the termination input amplifier is within the range of -10 to -17.5 volts.

General System Considerations

The foregoing requirements have been predicated on the use of low-capacitance, twisted-pair, shielded cable of no more than 300 feet in length. This interface system described should prove practical for 90 percent of applications. However, if a need should arise to use a cable greater than 300 feet in length or should peculiarities of the peripheral equipment dictate a slightly different interface approach, certain deviations may be required. Each such case should be carefully and individually evaluated in view of the basic principles.

MINUS 3 VOLT INTERFACE – INPUT AND OUTPUT CIRCUIT SPECIFICATIONS

Because of the rigorous timing restrictions in interfacing equipment with fast data transfer characteristics it is strongly recommended that designers, of equipment that is compatible with this feature in UNIVAC computers, use output line drivers and input amplifiers with parameters as specified in this section.

The -3 volt interface is characterized by nominal values of 0 volt and -3 volts to represent "1" and "0" respectively and by a switching threshold of -1.5 volts ± 0.4 volt. Each interface input amplifier circuit that takes its input from an interconnecting input cable will have the following characteristics:

- a) The output of the circuit will switch from "0" to "1" whenever the input signal changes in the positive direction through the range of -1.9 volts to -1.1 volts.
 - b) The output of the circuit will switch from "1" to "0" whenever the input signal changes in the negative direction through the range from -1.1 to -1.9 volts.
 - c) The output of the circuit will not switch as a result of any input transient-pulse signal that has an amplitude of less than 7.5 volts if its duration and amplitude are common to both sides of the line (common mode).
 - d) The output of the circuit will be "0" whenever its input is an open circuit.
 - e) The circuit will not draw more than 1.5 milliamperes for a steady state "1" nor more than 0.5 milliampere for a steady state "0".
 - f) The output of the circuit will be "0" whenever the steady state input signal is more negative than -1.9 volts.
 - g) The output of the circuit shall be "1" whenever the steady state input signal is more positive than -1.1 volts.
 - h) The input circuit will present a terminal impedance to the line equivalent to a resistance of 150 to 180 ohms in series with a capacitance of 0.0068 to 0.0100 microfarad.
- Each interface output line driver circuit will have the following characteristics when driving a line with any characteristic impedance between 120 ohms and 180 ohms.*
- a) The steady state output voltage representing "1" will be between 0.0 volt and -0.5 volt.
 - b) The steady state output voltage representing "0" will be between -3.0 volts and -4.5 volts. It may be more negative if the input circuit being driven presents a more negative signal not exceeding -7.0 volts.
 - c)* The circuit will be capable of supplying 1.5 milliamperes for a steady state "1" output.

*Each data line driver circuit that drives more than one line (e.g., four data lines per circuit in computers) must have proportionally more capability than specified here.

- d)* The circuit will be capable of sinking 0.5 milliamperes for a steady state "0" output.
- e) The output of the circuit will switch in not more than 0.4 microsecond (measured between the -0.5 volt and -3.0 volts amplitude points).
- f)* The circuit will be capable of driving the line and its termination (input amplifier) while switching as well as in the steady state condition.
- g) The circuit will present not less than 100,000 ohms impedance to the cable line whenever power is removed and the termination input amplifier is within the range of -3.0 to -7.0 volts.

PLUS 3.5 VOLT INTERFACE – INPUT AND OUTPUT CIRCUIT SPECIFICATIONS

The +3.5 volt interface is characterized by nominal values of 0 volt and +3.5 volts to represent binary "1" and binary "0" respectively, and by a switching threshold of +0.8 and +2.2 volts.

Each interface input amplifier circuit that takes its input from an interconnecting input cable must have the following characteristics:

- a) The output of the circuit switches from "0" to "1" whenever the input signal changes in the negative direction through the range of +2.2 volts to +0.8 volt.
- b) The output of the circuit switches from "1" to "0" whenever the input signal

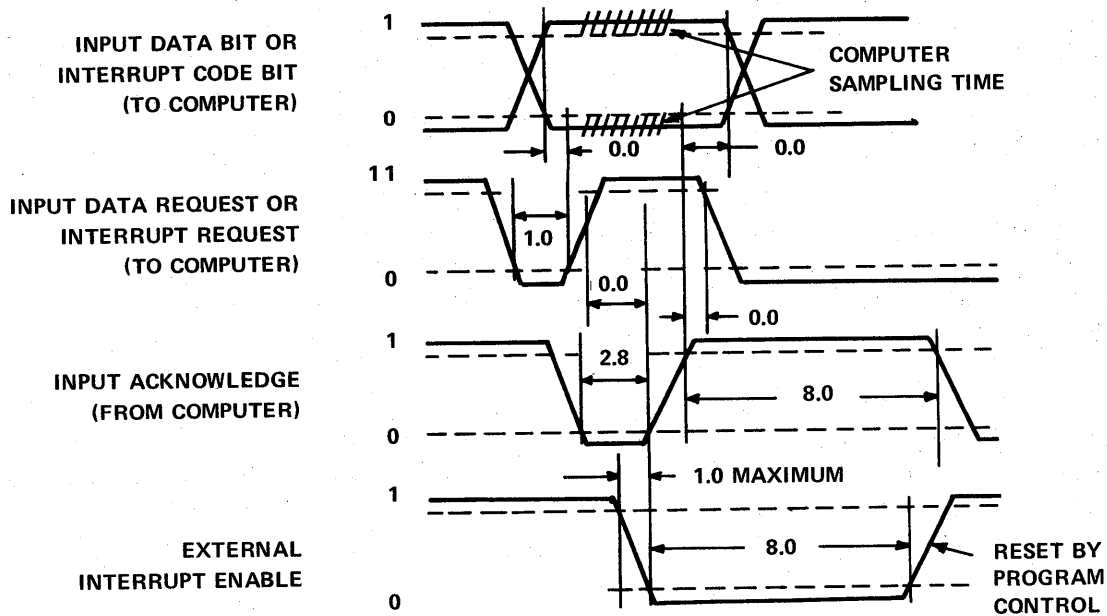
changes in the positive direction through the range of +0.8 volt to +2.2 volts.

- c) The output of the circuit will not switch as a result of any input transient-pulse signal that has an amplitude between +7.2 volts and -4.2 volts if its duration and amplitude are common to both sides of the line (common mode).
- d) The output of the circuit is "0" whenever its input is an open circuit.
- e) The circuit will not draw more than 2.5 milliamperes when a +3 volt signal is applied to the signal input terminal, and provides not more than 2.5 milliamperes when 0 volt is applied at the signal input terminal (return terminal grounded).
- f) The output of the circuit will be "0" whenever the steady state input signal is more positive than +2.2 volts.
- g) The output of the circuit will be "1" whenever the steady state input signal is more negative than +0.8 volt.
- h) The input circuit presents a terminal impedance to the line equivalent to a resistance of 110 to 160 ohms in series with a capacitance of 0.0068 to 0.01 microfarad.
- i) The input resistance of the signal input and return input terminals are matched to within ± 8 percent.

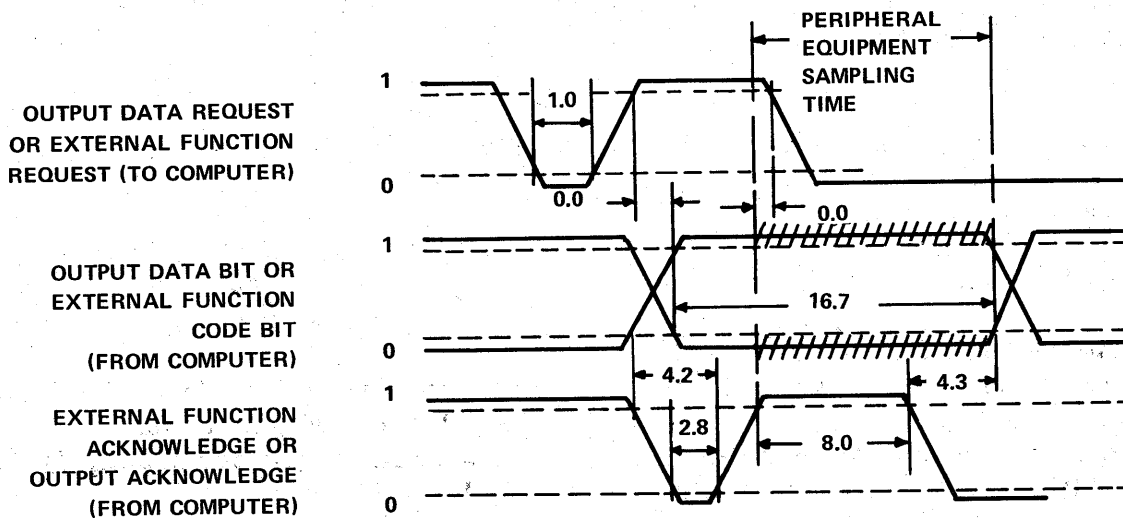
Each interface output line driver circuit must have the following characteristics when driving a line with any characteristic impedance between 110 to 160 ohms:*

*Each data line driver circuit that drives more than one line (e.g., four data lines per circuit in computers) must have proportionally more capability than specified here.

ALL NUMBERS ARE IN MICROSECONDS AND ARE MINIMUMS UNLESS OTHERWISE STATED.
TIME MEASURED AT THE 10 AND 90 PERCENT LEVELS OF THE SLOPES.



DATA AND INTERRUPT CODE INPUT



DATA AND EXTERNAL FUNCTION OUTPUT

FIGURE 3. -15 VOLT INTERFACE TIMING

- a)* The steady state output voltage representing "1" is between 0.0 and +0.45 volt. The output driver will sink a current of 40 milliamperes at the +0.45 volt level.
- b)* The steady state output voltage representing "0" is:
 - (1) Plus 2.7 volts minimum when supplying 27 milliamperes.
 - (2) Plus 4.5 volts maximum when supplying 1 milliampere.
- c)* The output voltage fall time (90% to 10%) will be less than 100 nanoseconds when the output of the line driver is loaded with a 100-ohm resistor connected to a 4-volt source.
- d)* The output voltage rise time (10% to 90%) will be less than 100 nanoseconds when the output of the line driver is loaded with a 100 ohm resistor connected to ground.
- e)* The circuit is capable of driving the lines and terminations (input amplifier) while switching 27 milliamperes at 250 kilocycles per second, as well as in the steady state condition.
- f) The circuit will present not less than 100,000 ohms impedance to the cable line whenever power is removed and the termination input amplifier is within the range of +3.0 to +7.0 volts.

TIMING OF INPUT AND OUTPUT DATA AND CONTROL LINES

Specific references are made to Figures 3, 4, and 5 and to certain items in Table 3 to describe the order of events and timing characteristics for the computer interfaces available. These references are

*Each data line driver that drives more than one line (e.g., four data lines per circuit in computers) must have proportionally more capability than specified herein.

noted throughout the discussion, as required, to explain each type of input/output activity. Definitions of control signals are found in Table 1.

Durations of signals and time between signals in any communication sequence will comply with the applicable limits specified in Figures 3, 4, and 5. These limits are neither absolute nor necessarily typical, but rather they are minimums that denote the following dual requirements.

- a) Neither the initiation nor the termination of any control or data signal may occur sooner than specified.
- b) Each device must be capable of recognizing data and control signals that occur at or any time later than specified, and that exist for any duration equal to or greater than specified.

Output of Data and External Equipment Commands

The discussion which follows pertains to the timing involved in the transfer of both data words and External Function (EF) words. A peripheral device sets the Output Request line or External Function Request line when it is in a condition to accept a data or External Function word from the computers. The Output or External Function Acknowledge signal indicates to the peripheral equipment that the requested word is present on the data lines, which should now be sampled. Figures 3 and 4 show the waveforms for both data and command code transfers to peripheral equipment.

No delay is required between detection of the Output or External Function Request signal and the placement of answering data on the lines. The maximum time depends upon the computer program, the priority of the particular channel, and the data rates of peripheral equipment on other channels. Computer logic, however, delays setting the Output and External Function Acknowledge control line after placing data or command codes in its output register as shown in Item 1 of Table 3.

Peripheral equipment must be capable of recognizing, as an Output or an External Function Acknowledge, a signal which may exist in the stable "one" state for a limited time (Item 3). The computer will maintain stable data on the lines for a minimum time after it starts to drop the Output or External Function Acknowledge (Item 2). An output word will be available to the peripheral equipment in a stable state for an interval which may be as short as shown in Item 4 Table 3 if the computer is performing output operations at a maximum rate.

The peripheral device may drop the Output or External Function Request to the "zero" state any time after detecting the Output or the External Function Acknowledge. The Output or External Function Request cannot be reset immediately to indicate readiness to accept another word because the computer will not respond to another Output or External Function Request unless a minimum time delay (Item 7) is allowed for clearing the line. The waveforms show that the timing would allow equipment that wishes to receive data from the computer at a maximum rate to set the Output or External Function Request to the "one" state for the second time before the first Output or External Function Acknowledge has dropped to the "zero" state. However, this will not affect operation of the cycle since the minimum delay will again exist between the availability of the next word on the data lines and setting the next Output or External Function Request.

Devices having no provision for sending an External Function Request signal require computer programs that utilize the "External Functions with Force" instruction in order to command the device. External Functions with Force require no request from the peripheral equipment. The computer places the External Function code on the output lines, and a minimum time later (Item 1) sets the External Function Acknowledge line.

The peripheral equipment has no control over the rate at which "External Functions with Force" are sent. If two such computer instructions to the same peripheral device are executed consecutively, the resulting signal may be in the "zero" state for an interval which may be as short as shown in Item 6 of Table 3. If the peripheral equipment cannot accept External Functions at this rate, restrictions must be made in the programming of External Function instructions to the equipment.

Input of Data and Interrupt Status Codes to Computer

The Input Request signal indicates to the computer that data have been placed on the input lines. The Input Acknowledge indicates to peripheral equipment that the computer's data lines have been sampled. To ensure that the data will be accepted, the Input Request and the data must be maintained on the lines until an answering Input Acknowledge is received. When sending data to the computer, the input device may set the Input Request at the same time the data are placed on the lines or it may set the Input Request after the data lines are set. Figure 4 shows the waveforms for data or interrupt code and control lines to peripheral equipment. There is no delay required between sensing of the Input Request and the answering Input Acknowledge.

The Input Acknowledge signal is set for a fixed time interval. Peripheral equipment must be capable of detecting, as an Input Acknowledge, a signal which may exist in the stable "one" state for as little as shown in Item 3. The peripheral device may drop the Input Request line and the data lines to the "zero" state any time after detecting the Input Acknowledge. The Input Request cannot be reset immediately to indicate input of another data word because the computer will not respond to another Input Request unless a time delay as shown in Item 7 is allowed for

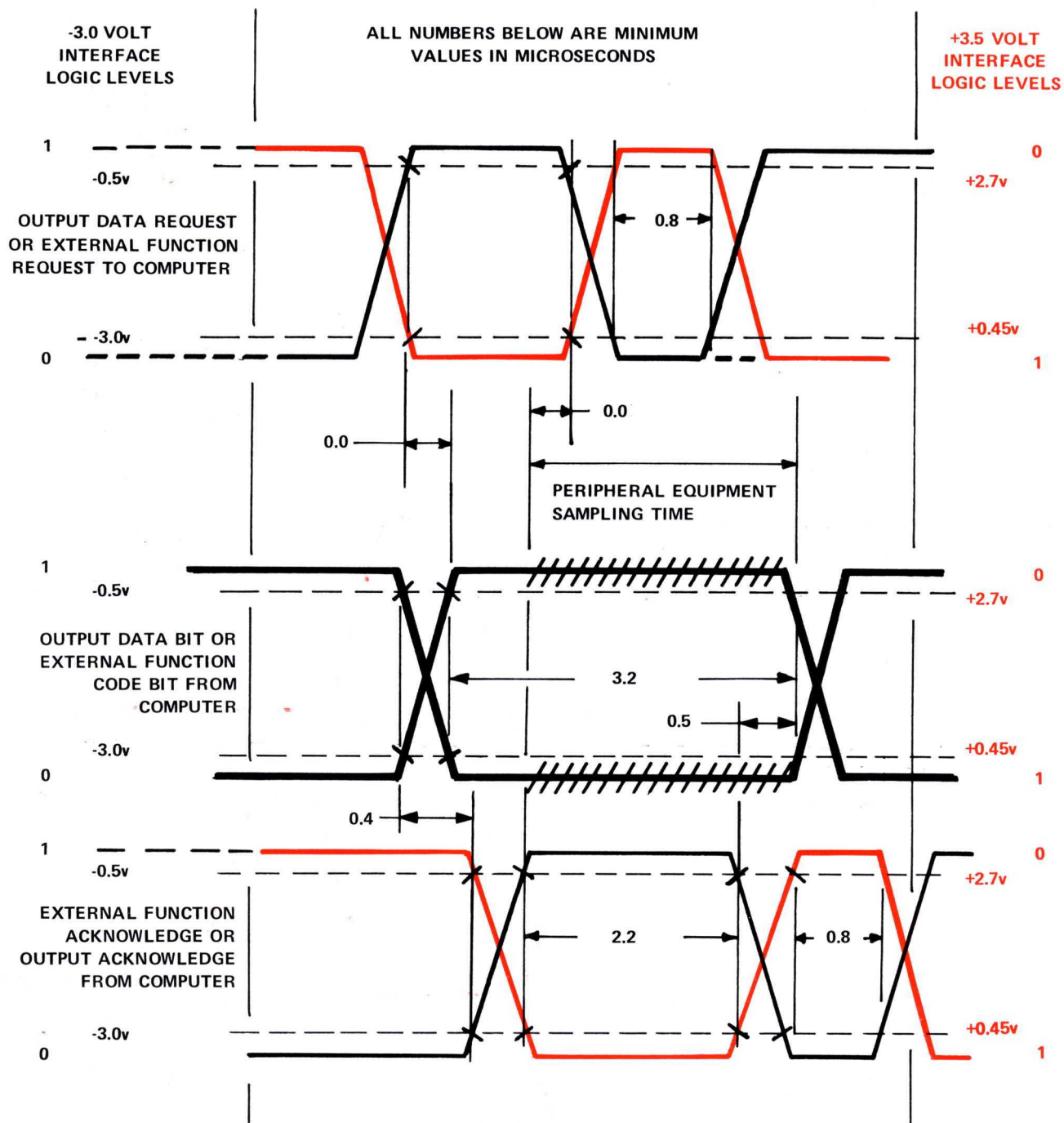


FIGURE 4. OUTPUT DATA AND EXTERNAL FUNCTION TIMING
(-3.0 VOLT INTERFACE)
(+3.5 VOLT INTERFACE)

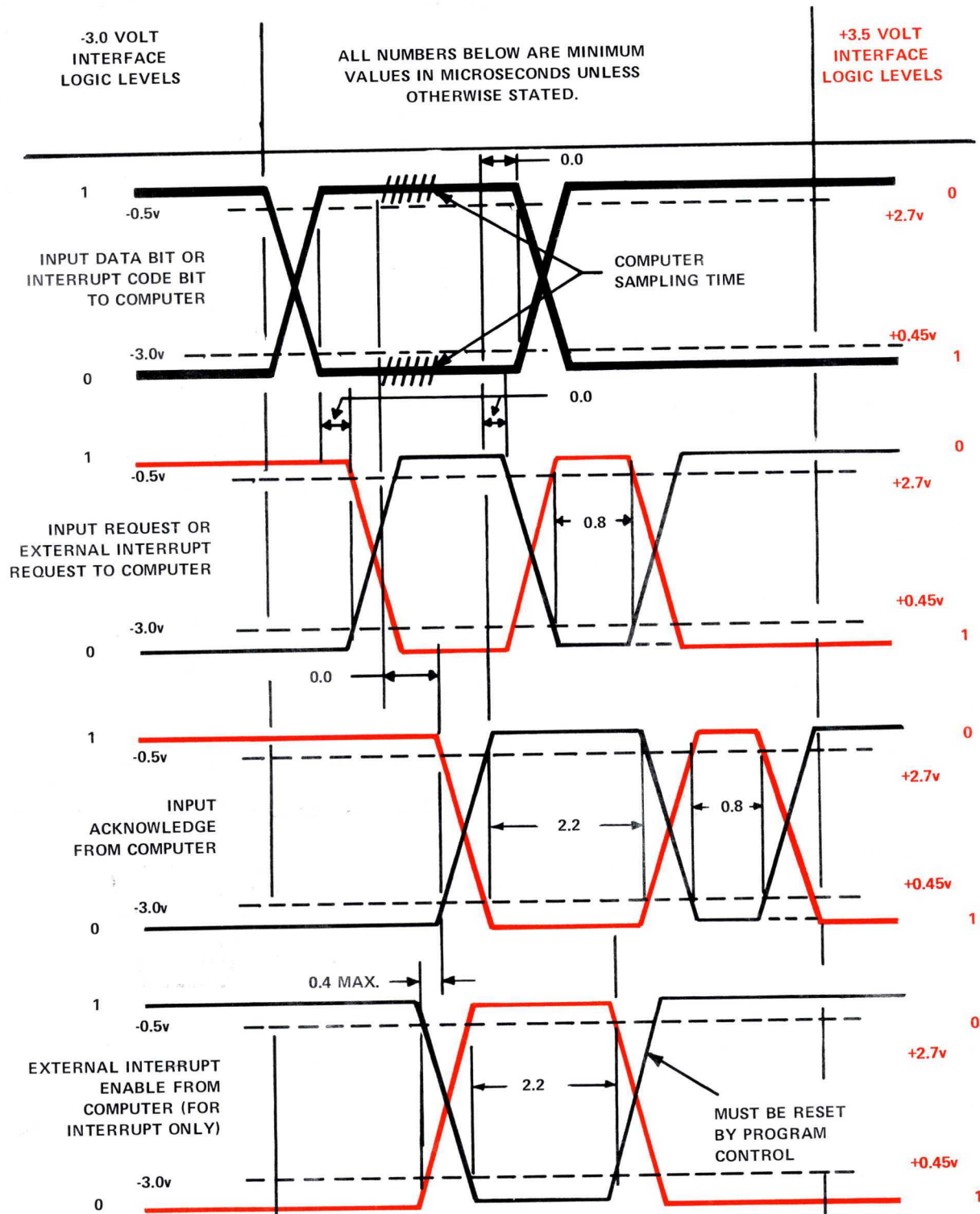


FIGURE 5. INPUT DATA AND EXTERNAL INTERRUPT TIMING
(-3.0 VOLT INTERFACE)
(+3.5 VOLT INTERFACE)

clearing the line. The waveforms show that the timing would allow peripheral equipment wishing to transmit data at a maximum rate to set the Input Request to the "one" state for the second time before the first Input Acknowledge had dropped to the "zero" state. However, this will not affect operation of the cycle since the Input Request circuitry had been reset for further sensing when the Input Acknowledge was set.

If it becomes necessary to interrupt the computer after data have been presented with an Input Request and not yet acknowledged by the computer, the Input Data Request line must be cleared by the peripheral device at least 20 microseconds prior to setting the Interrupt code and the Interrupt Request lines. This will prevent the computer from interpreting the Interrupt code as a data word.*

Two methods of controlling the transmission of External Interrupts from peripheral equipment to the computer are used. Some computers are designed with the Interrupt Enable signal that indicates ability to honor an interrupt on a specific channel. Others do not inform the peripheral devices of this state. When sending an interrupt, the peripheral equipment may either place the Interrupt code on the data lines and then set the External Interrupt Request line, or set both simultaneously. In either case, the data lines may not be changed while the Interrupt Request line is set. The computer accepts the Interrupt code (at its convenience) and drops the Interrupt Enable. To ensure that the Interrupt code will be accepted, the Interrupt signal must be

maintained on the line until the Interrupt Enable is dropped and the Input Acknowledge is set (a synchronized occurrence). There is no delay required between sensing the Interrupt Request line and the dropping of the Interrupt Enable. Any delayed reaction time for a particular cycle, is determined by interaction with the computer program and the other input/output channels.

When the computer sets the Input Acknowledge signal to inform the peripheral equipment that it has accepted the Interrupt code, it clears the Interrupt Enable and will not reset it again until the computer program enables it. Peripheral equipment may be designed to initiate an interrupt transfer without monitoring the Interrupt Enable line from the computer. This does not alter the timing sequence since the computer still accepts the Interrupt code at its own convenience.

For certain computers the minimum timing shown for the External Interrupt Enable line in Figures 3 and 5 can be altered by program intervention. If the next instruction following an External Interrupt is "Remove Interrupt Lockout", these computers are capable of resetting the External Interrupt Enable line before the minimum specified. In fact, using the -15 volt interface, these computers can reset the line before the peripheral equipment is capable of detecting it. (It may have been momentarily, or only partially cleared.) Consequently, for -15 volt interface, the input amplifier for an External Interrupt Enable line from these computers must not be a one-shot amplifier.

PHYSICAL INTERFACE

An input/output channel of any digital UNIVAC Defense Equipment shall be able to interconnect with an input/output channel of any compatible equipment by means of a pair of cables. The

interconnected equipment transfers input data and associated control signals on one cable, and transfers output data and associated control signals on the other cable.

*Applicable also in the converse situation.

TABLE 3. I/O CONTROL AND DATA LINE TIMING

ITEM	DESCRIPTION	MINIMUM TIME IN MICROSECONDS	
		-15 VOLT INTERFACE	-3 VOLT & +3.5 VOLT INTERFACE
	COMPUTER		
	1 Delay - from setting data or command code on output lines to setting the Output or External Function Acknowledge	4.2	0.4
	2 Delay - from dropping the Output or External Function Acknowledge to Dropping the data or code on output lines.	4.3	0.5
	3 Input, Output or External Function Acknowledge in stable "1" state on control lines.	8.0	2.2
	4 Data or function codes on output lines in stable "1" state.	16.7	3.2
	EXTERNAL FUNCTIONS W/FORCE		
	5 Delay - from dropping the External Function Acknowledge to dropping the command code.	4.3	0.5
	6 Consecutive External Functions with force; External Function Acknowledge lines in "0" state.	2.8	0.8
	PERIPHERAL EQUIPMENT (Recommended)		
	7 Delay - from dropping the Input Request, External Function Request, or Output Request to resetting.	7.0	1.2
	ALL EQUIPMENT WITH COMMON INTERFACE	MAXIMUM TIME IN MICROSECONDS	
	8 Transition Time of control and data line signals.	6.0	0.4
	9 Transition Rate of control and data line signals (volts per microsecond).	5.0	--

TABLE 4. INTERFACE CIRCUITS AND CABLE LENGTHS

UNIVAC Printed Circuit Assembly		Maximum length (feet) of Cable per Univac specification*			
		DS – 5177 Superseded by 7956687 80 Conductor	DS-5192 Superseded by 7956691-00 84 Conductor 7956691-01 90 Conductor	7956256 90 Conductor	7956785 120 Conductor
Part Number	Description				
-15 Volt Interface Drivers					
4222130	Control Line	300	50	300	300
4222131	Control Line	300	300	300	300
4222140	Data Line	300	50	300	300
4222141	Data Line	300	300	300	300
7002130	Control Line	300	50	300	300
7002131	Control Line	300	300	300	300
7002140	Data Line	300	50	300	300
7002141	Data Line	300	300	300	300
★ 7111520	Data & Control	300	150	300	300
7500830	Data Line	300	300	300	300
7500840	Control Line	300	300	300	300
-15 Volt Input Amplifiers					
4222090					
7002090					
★ 7111530					
7500850					
7500310	Timing Control	---	---	---	---
-3 Volt Interface Drivers					
4222330	Control Line	150	50	50	50
4222340	Data Line	150	50	50	50
7002331	Control Line	150	50	50	50
7002332	Control Line	200	150	200	200
7002341	Data Line	150	50	50	50
7002342	Data Line	200	150	200	200
★ 7111505	Data & Control	300	150	300	300
7500800	Data Line	300	150	300	300
7500810	Control Line	300	150	300	300
-3 Volt Input Amplifiers					
4222320					
7002321					
★ 7111515					
7500820					
7500910	Timing Control	---	---	---	---
+3.5 Volt Interface Drivers					
★ 7113330	Data & Control	300	150	300	300
7111105	Control Line	100	50	100	100
(LD-1A Bussed)					
7111185	Driver & Input	100	50	100	100
(LD-1A Not Bussed)	Amp. (Data)				
+3.5 Volt Input Amplifiers					
★ 7113335					
7111075					
7111041	Timing Control	---	---	---	---

*Specification Drawing does not include terminal connectors.

TABLE 5. CONNECTOR PIN ASSIGNMENTS

FUNCTION		120 PIN		90 PIN		85 PIN	
INPUT CHANNEL CONNECTOR	OUTPUT CHANNEL CONNECTOR	SIGNAL	RETURN	SIGNAL	RETURN	SIGNAL	RETURN
IN. DATA REQ.	OUT. ACK.	B-5	A-5	1	11	1	6
IN. ACK.	OUT. DATA REQ.	B-6	A-6	2	12	2	7
EXT. INT. REQ.	EXT. FUNCT. ACK.	B-7	A-7	3	13	3	8
EXT. INT. ENABLE	EXT. FUNCT. REQ.	B-8	A-8	4	14	4	9
DATA BIT 00		D-1	C-1	9	19	13	21
DATA BIT 01		D-2	C-2	10	20	14	22
DATA BIT 02		D-3	C-3	22	33	15	23
DATA BIT 03		D-4	C-4	23	34	16	24
DATA BIT 04		D-5	C-5	24	35	17	25
DATA BIT 05		D-6	C-6	25	36	18	26
DATA BIT 06		D-7	C-7	26	37	29	39
DATA BIT 07		D-8	C-8	27	38	30	40
DATA BIT 08		D-9	C-9	28	39	31	41
DATA BIT 09		D-10	C-10	29	40	32	42
DATA BIT 10		D-11	C-11	30	41	33	43
DATA BIT 11		D-12	C-12	31	42	34	44
DATA BIT 12		G-1	H-1	32	43	35	45
DATA BIT 13		G-2	H-2	47	58	36	46
DATA BIT 14		G-3	H-3	48	59	37	47
DATA BIT 15		G-4	H-4	49	60	49	58
DATA BIT 16		G-5	H-5	50	61	50	59
DATA BIT 17		G-6	H-6	51	62	51	60
DATA BIT 18		G-7	H-7	52	63	52	61
DATA BIT 19		G-8	H-8	53	64	53	62
DATA BIT 20		G-9	H-9	54	65	54	63
DATA BIT 21		G-10	H-10	55	66	55	64
DATA BIT 22		G-11	H-11	56	67	56	65
DATA BIT 23		G-12	H-12	57	68	57	66
DATA BIT 24		J-1	K-1	70	80	67	75
DATA BIT 25		J-2	K-2	71	81	68	76
DATA BIT 26		J-3	K-3	72	82	69	77
DATA BIT 27		J-4	K-4	73	83	70	78
DATA BIT 28		J-5	K-5	74	84	71	79
DATA BIT 29		J-6	K-6	75	85	72	80
DATA BIT 30		J-7	K-7	76	86	73	81
DATA BIT 31		J-8	K-8	77	87	5	12
DATA BIT 32		J-9	K-9	5	15	10	11
DATA BIT 33		J-10	K-10	6	16	82	83
DATA BIT 34		J-11	K-11	7	17	19	27
DATA BIT 35		T12	K-12	8	18	84	85
SHIELD			B-1		45		74
SHIELD			A-1*		69*		
SPARE	Refer to the individual cable drawing	B-2	A-2	21	Not Used	20	Not Used
SPARE		B-3	A-3	44		28	
SPARE		B-4	A-4	46		38	
SPARE		B-9	A-9	78		48	
SPARE		B-10	A-10	79			
SPARE		B-11	A-11	88			
SPARE		B-12	A-12	89			
SPARE		F-1	E-1	90			
SPARE		F-2	E-2				
SPARE		F-3	E-3				
SPARE		F-4	E-4				
SPARE		F-5	E-5				
SPARE		F-6	E-6				
SPARE		F-7	E-7				
SPARE		F-8	E-8				
SPARE		F-9	E-9				
SPARE		F-10	E-10				
SPARE		F-11	E-11				
SPARE		F-12	E-12				

*Pins A-1 and 69 are Secondary Shield connections.

Data bits and control lines not used by a device will have no connection

INTERCONNECTING CABLES

The allowable length of interconnection cables depends upon both the electrical characteristics of the cable and the driving circuits. Table 4 lists maximum allowable cable lengths for a variety of cables and interface driver circuit combinations used in UNIVAC equipment. Reliable information transfers are assured when compatible drivers and cables are used in systems which are also grounded in accordance with UNIVAC specification SB-10131.

Reliable transfers on cables longer than indicated in the table may be achieved in some cases.

Greater dependence is placed on grounding techniques, equipment in the system, equipment layout and environmental conditions. Each such case must be analyzed separately to determine maximum allowable cable lengths.

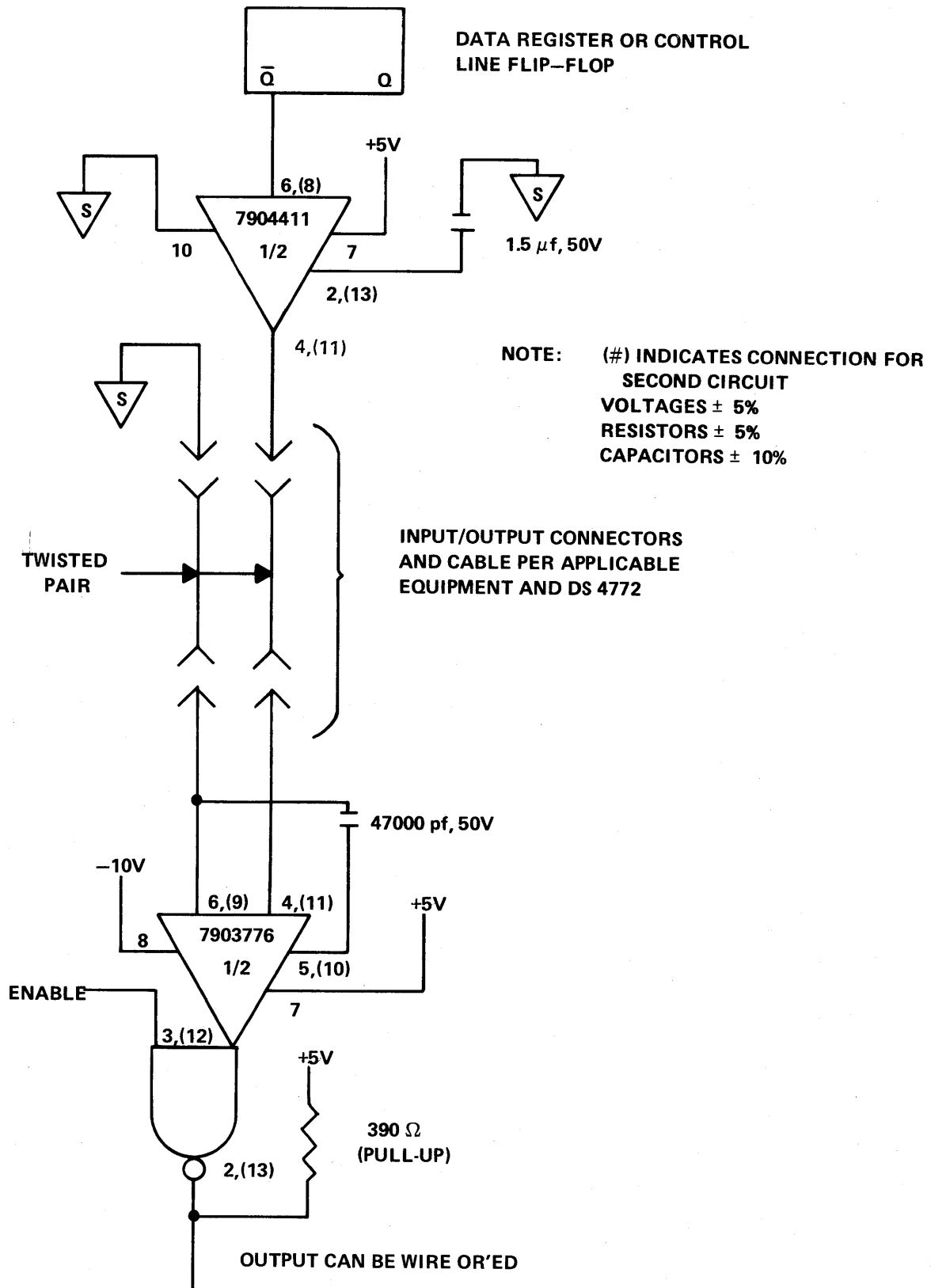
CABLE CONNECTORS

The input/output channel connectors mounted on UNIVAC equipment are given the data bit and control signal assignments as specified in Table 5. Where a channel has fewer control lines or less than 36 data lines, pins assigned to unused lines have no connections. Table 6 lists drawings of matching connectors.

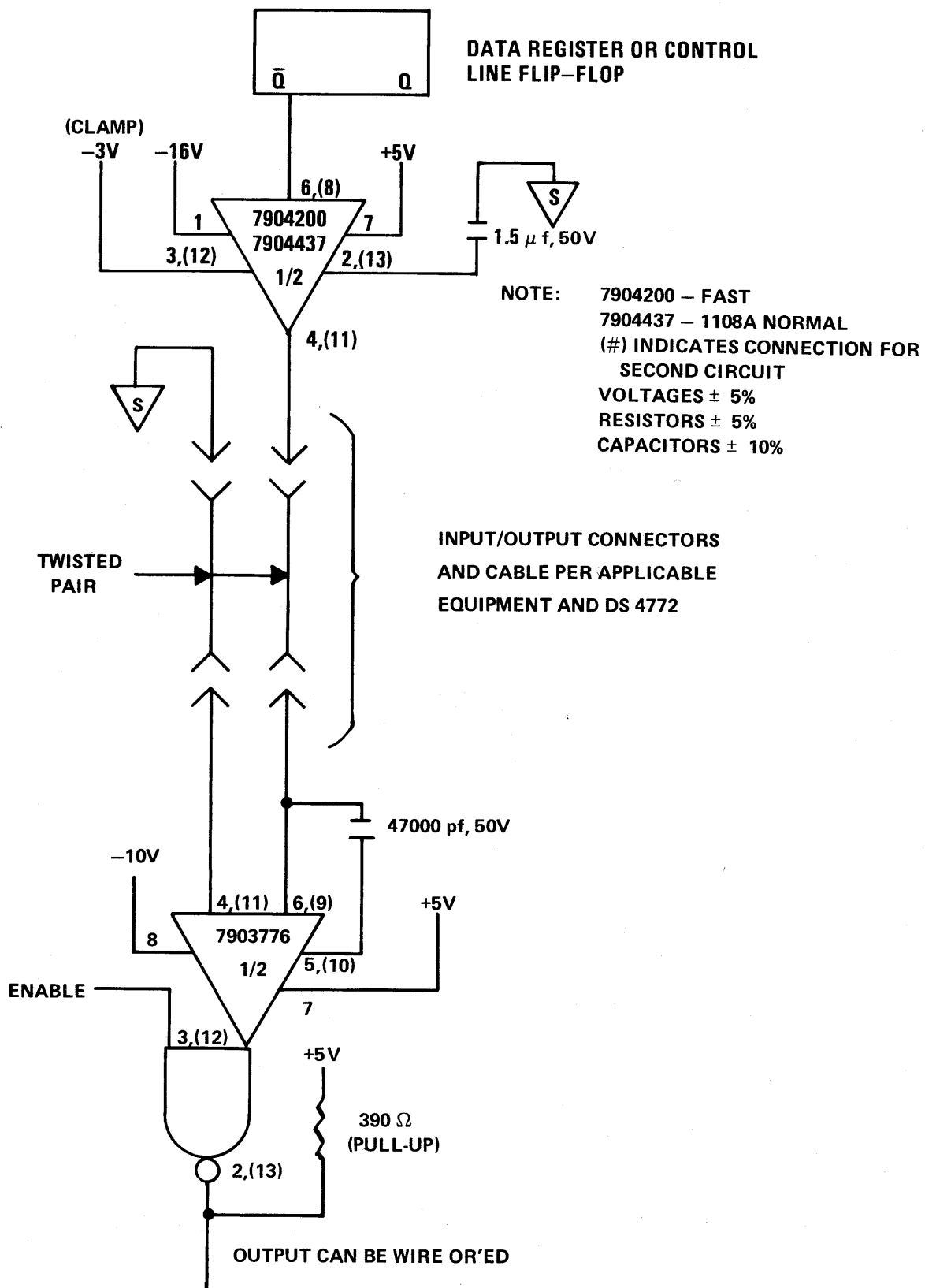
TABLE 6. CABLE AND CABINET CONNECTORS

CABLE MOUNTED FEMALE CONNECTOR DRAWING	CONNECTOR DESCRIPTION	CABINET MOUNTED MALE CONNECTOR DRAWING
259056-12	90 pin	908221
7084908-01	120 pin, small cable	7902244
7084865	120 pin, small cable	7902244
7084908-00	120 pin, large cable	7902244
7214384-00	85 pin, input	7902698-00
7214384-01	85 pin, output	7902698-01

TYPICAL +3.5 VOLT (ANew) INTERFACE CIRCUIT
IN UNIVAC DSD COMPUTERS AND PERIPHERALS



**TYPICAL -3 VOLT (NTDS FAST OR 1108A) INTERFACE CIRCUIT
IN UNIVAC DSD COMPUTERS AND PERIPHERALS**



TYPICAL -15 VOLT (NTDS SLOW) INTERFACE CIRCUIT
IN UNIVAC DSD COMPUTERS AND PERIPHERALS

